

Three Derivations of Principal Component Analysis

Why are the PCA basis vectors the eigenvectors of the correlation matrix?

Derivation #1: by maximizing variance

From Ballard & Brown, Computer Vision: The (random) data vector is x ; its component along a proposed axis u is $(x \cdot u)$. The variance of this is $E(x \cdot u - E(x \cdot u))^2$ (the variance is the expectation of the square of the data with its mean removed).

$$\begin{aligned} E(x \cdot u - E(x \cdot u))^2 &= E[(u \cdot (x - Ex))^2] \\ &= uE[(x - Ex) \cdot (x - Ex)^T]u \\ &= u^T C u \end{aligned}$$

C is the covariance or 'correlation' matrix. The u that gives the maximum value to $u^T C u$ (with the constraint that u is a unit vector) is the eigenvector of C with the largest eigenvalue. The second and subsequent principal component axes are the other eigenvectors sorted by eigenvalue.

#2: ...by error minimization

Find PCA basis vectors u that minimize $E\|x - \hat{x}\|^2$ for a partial expansion out to P components:

$$\begin{aligned} \hat{x} &= \sum_{k=1}^P (x \cdot u_k) u_k \\ x - \hat{x} &= \sum_{k=P+1}^N (x \cdot u_k) u_k \end{aligned}$$

where N is the full set of vectors necessary to represent the data.

So, minimize the square of the last sum. The cross terms disappear because of the orthogonality of u_k . For each term:

$$E((x \cdot u)u)^2 = E u (x \cdot u) (x \cdot u) u$$

the outer u 's disappear because $u \cdot u = 1$.

$$= E(x \cdot u)(x \cdot u) = u C u$$

But $u C u = \lambda$, so the truncation error is the sum of the lower eigenvalues! Why: we know that u are eigenvectors, so they satisfy $C u = \lambda u$, also $u \cdot u = 1$, so....

#3: ...by diagonalizing the correlation matrix

The correlation matrix of some data: $C = E[xx^T]$. The correlation matrix of the data x transformed by some transform T : $C' = E[Tx(Tx)^T] = E[Txx^T T^T]$. The inner xx^T is the correlation matrix of the original data. Now suppose that the rows of T are chosen to be the eigenvectors of this correlation matrix— then because of the orthogonality of the eigenvectors, the resulting matrix C' will be diagonal. Thus C' , the correlation matrix of the transformed data, is uncorrelated. So the basis that diagonalizes the correlation matrix consists of the eigenvectors of the (original) correlation matrix.

Correlation matrices

For a vector x , Exx^T is a correlation matrix.

Say M is a matrix whose columns contain data vectors. I think both MM^T and $M^T M$ can be interpreted as correlation matrices.

MM^T is the usual correlation matrix, a sum of outer products:

$$(MM^T)_{i,j} = \sum_k x_k[i]x_k[j]$$

$$(MM^T) = \sum_k x_k x_k^T \approx Exx^T = C$$

If x_k are a sliding window through a signal, i.e. x_0 contains samples 0..10, x_1 samples 1..11, etc., then this corresponds to estimating the autocovariance of the signal. If x_k are images scanned into a vector, this gives the average (after dividing by N) correlation of pixel i with pixel j .

The i, j entry of $M^T M$ is the dot of data vector i with data vector j . If a column of M contains various measurements for a particular person then $(M^T M)_{i,j}$ gives the correlation, averaged across tests, of person i with person j , while $(MM^T)_{i,j}$ gives the correlation, averaged across people, of test i versus test j .

PCA and SVD

SVD decomposes a possibly non-square matrix M into USV where U, V are square rotation-like matrices and S is a diagonal matrix of singular values. The columns of U are the eigenvectors of MM^T , the columns of V are the eigenvectors of $M^T M$.

Computation Trick

If we are computing PCA on an image, M will be (e.g.) a million by N (N images), and MM^T will be million². Instead, first find the eigenvectors of $M^T M$ (which is $N \times N$): $M^T M x = \lambda x$. Then premultiply by M and interpret as $(MM^T)(Mx) = \lambda(Mx)$, i.e., Mx are the desired eigenvectors, now given as a linear combination of the original data using weights which are the eigenvector of the smaller system.